

OPTIMAL FIR-FILTER DESIGN SUBJECT TO INEQUALITY CONSTRAINTS BY MEANS OF THE COMPLEMENTARITY ALGORITHM

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For an optimal design of digital FIR filters a new method is proposed. On the base of the equations for FIR filters with linear phase the idealized frequency response is approximated via a least-squares solution with inequality constraints (ICLS-solution). The advantages of this method are:

- (i) one obtains optimal impulse response coefficients in the sense of an idealized frequency approximation,
- (ii) it can be used easily for the design of optimal two-dimensional FIR filters.

While the design of optimal Chebyshev FIR filters makes use of the REMEZ Exchange Algorithm, efficient algorithms for the ICLS-solution are available, too, particularly those of [1] and [5], as described by [6]. The extension of the REMEZ Exchange Algorithm for a two-dimensional frequency approximation is difficult so that point (ii) is an important feature of this method.

The approximation problem of an idealized frequency response with an ICLS-solution is solved by means of Lemke's linear complementarity algorithm. This procedure differs completely from that of [3,4] developed for a similar case; confer also with [2]. The application is demonstrated by the following example.

Example: Design of a 24-point linear phase lowpass filter with passband cutoff frequency of 0.08 and stopband cutoff frequency of 0.16 and ripple ratio of 1.0.

Table 1 shows the solutions of the impulse response and their confrontation with the optimal Chebyshev solution taken from [7] (including the run time on a PDF11 64 KByte computer). The ICLS-solution was obtained from a simple least-squares solution (LS-solution) by add of 18 inequality constraints within the frequency response.

Parts of the frequency response of the LS- and ICLS-solution are figured in Fig.1.

As shown by table 1 and Fig.1b the ICLS-solution comes up to an optimal Chebyshev solution.

References:

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Table 1: Solutions for the impulse response

|  | LS-solution | ICLS-solution | Chebyshev solution |       |
|--|-------------|---------------|--------------------|-------|
| h(1)   | 0.004544    | 0.005068      | 0.003374           | h(24) |
| h(2)   | 0.009389    | 0.010702      | 0.014938           | h(23) |
| h(3)   | 0.010116    | 0.011664      | 0.010569           | h(22) |
| h(4)   | 0.002094 ✓  | 0.003090      | 0.002542           | h(21) |
| h(5)   | -0.014654 ✓ | -0.014728     | -0.015930          | h(20) |
| h(6)   | -0.032364 ✓ | -0.033422     | -0.034085          | h(19) |
| h(7)   | -0.036970 ✓ | -0.038406     | -0.038112          | h(18) |
| h(8)   | -0.014707 ✓ | -0.015820     | -0.014629          | h(17) |
| h(9)   | 0.039111 ✓  | 0.038705      | 0.040090           | h(16) |
| h(10)  | 0.114442 ✓  | 0.114694      | 0.115407           | h(15) |
| h(11)  | 0.188270 ✓  | 0.188900      | 0.188507           | h(14) |
| h(12)  | 0.234014 ✓  | 0.234774      | 0.233546           | h(13) |
| Band 1                      Band 2                   |             |               |                    |       |
| Lower band edge                                      | 0.00        | 0.16          |                    |       |
| Upper band edge                                      | 0.08        | 0.50          |                    |       |
| Desired value  | 1.00        | 0.00          |                    |       |
| Weighting  | 1.00        | 1.00          |                    |       |
| Deviation $ \delta_{\max} $ for the solutions above: |             |               |                    |       |
|  | 0.023182    | 0.012500      | 0.012434           |       |
| Time:  | 60 [sec]    | 75 [sec]      | 140 [sec]          |       |

Fig. 1: Parts of the frequency response

