

The EuroSDR network on Digital Camera Calibration and Validation



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Experimental Phase 2b data



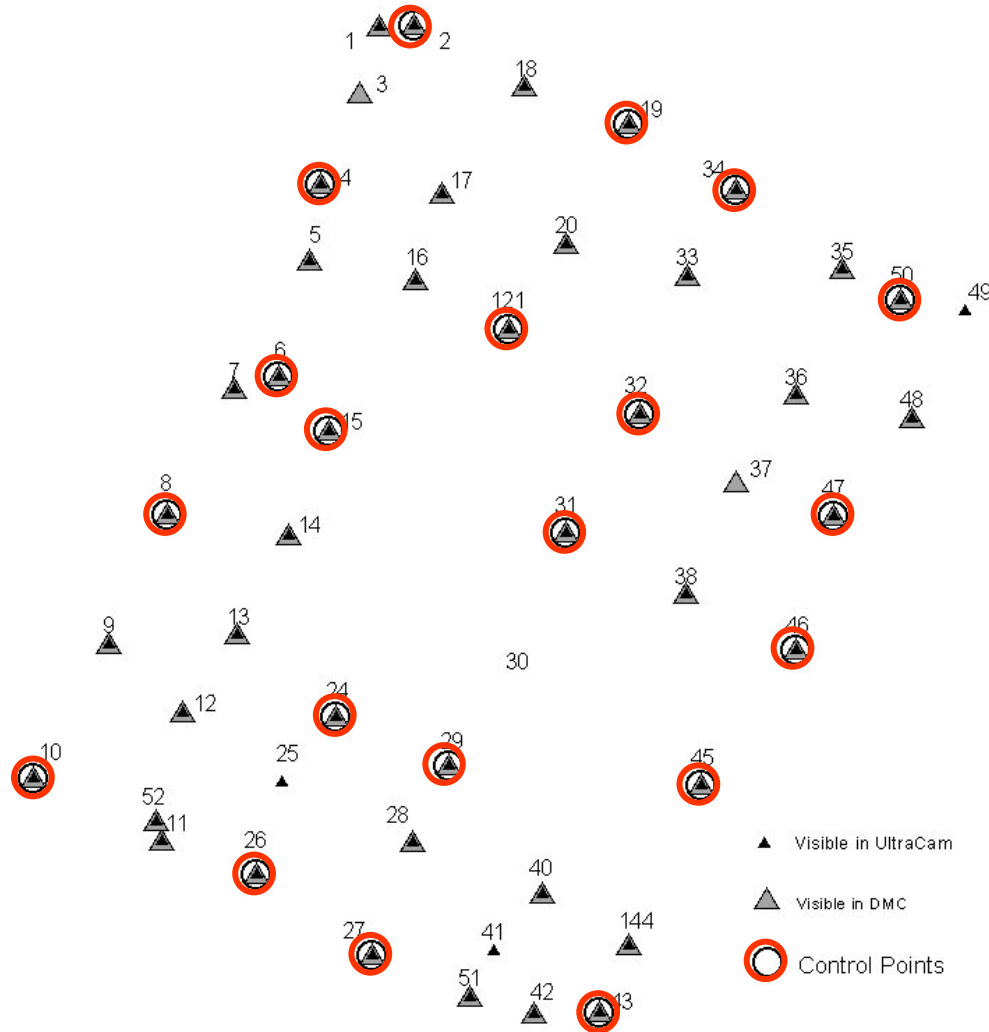
#	Altitude [m]	GSD [m]	# strips long/cross	% overlap long/cross	# Images	Additional data
ADS Vaihingen/Enz, June 26, 2004						
<i>low</i>	1500	0.18	4 / 2	100 / 44	36	GPS/INS
<i>high</i>	2500	0.26	3 / 3	100 / 70	36	GPS/INS
DMC Fredrikstad, October 10, 2003						
<i>low</i>	950	0.10	5	60 / 30	115	(GPS(/INS))
<i>high</i>	1800	0.18	3	60 / 30	34	(GPS(/INS))
UltracamD Fredrikstad, September 16, 2004						
<i>low</i>	1900	0.17	4 / 1	80 / 60	131	GPS(/INS)
<i>high</i>	3800	0.34	2	80 / 60	28	GPS(/INS)



The Fredrikstad test range



DMC and UCD flights



object points

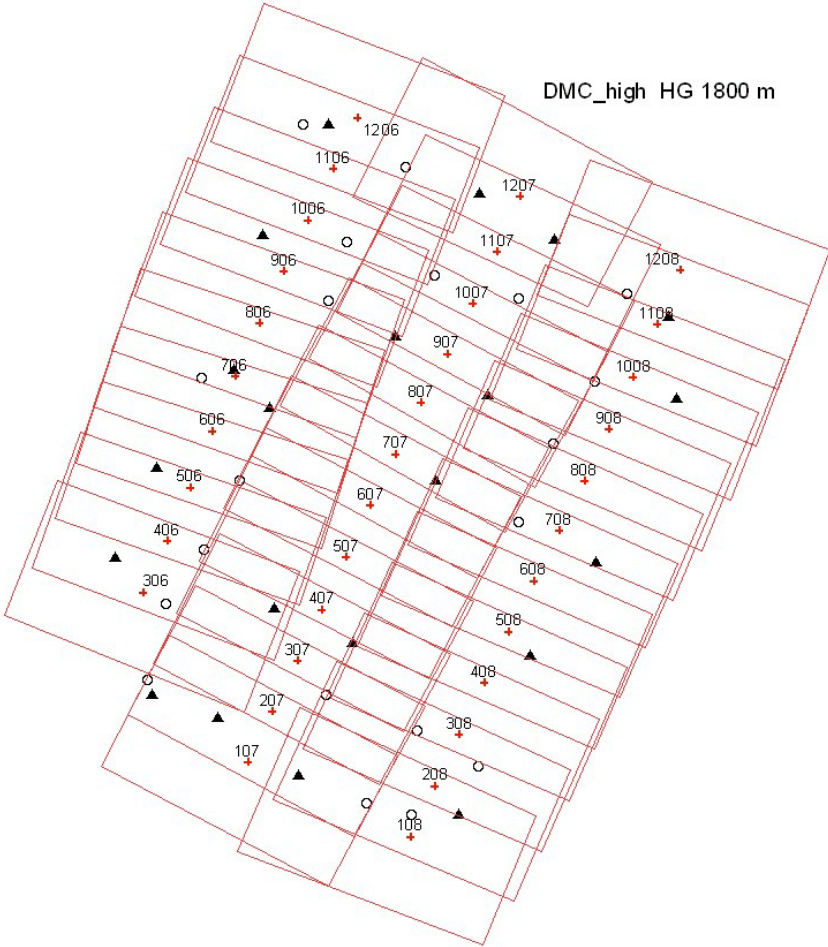
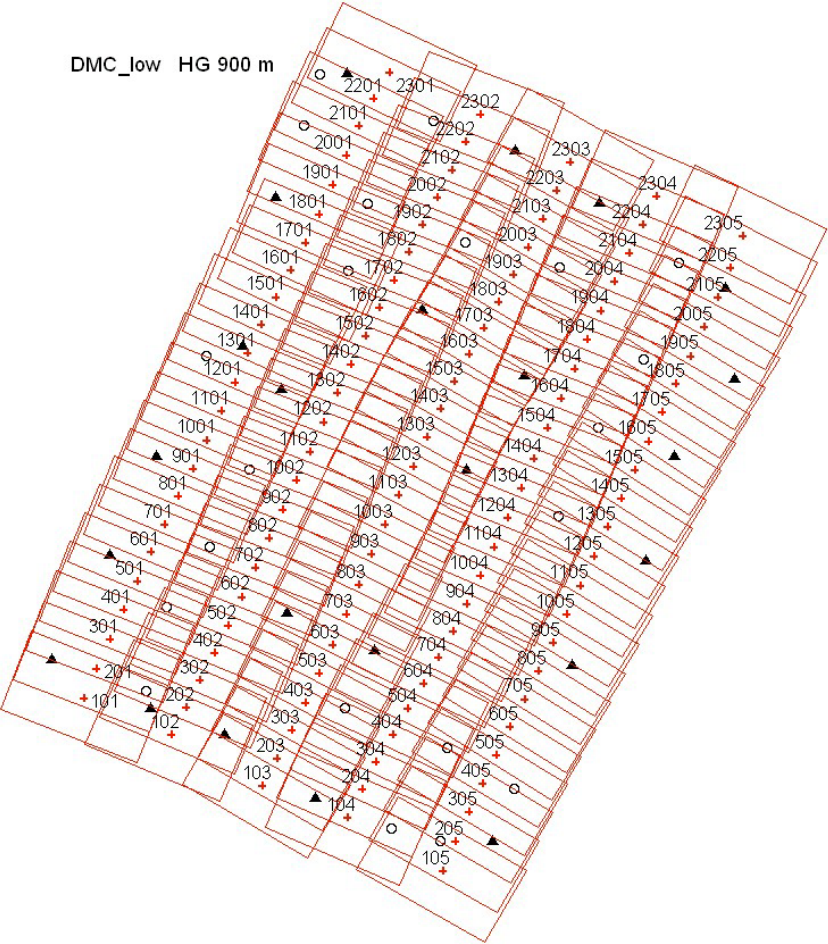
~ 20 control points

~ 25 check points





DMC image block geometry



Low (GSD 10cm, h=950m)

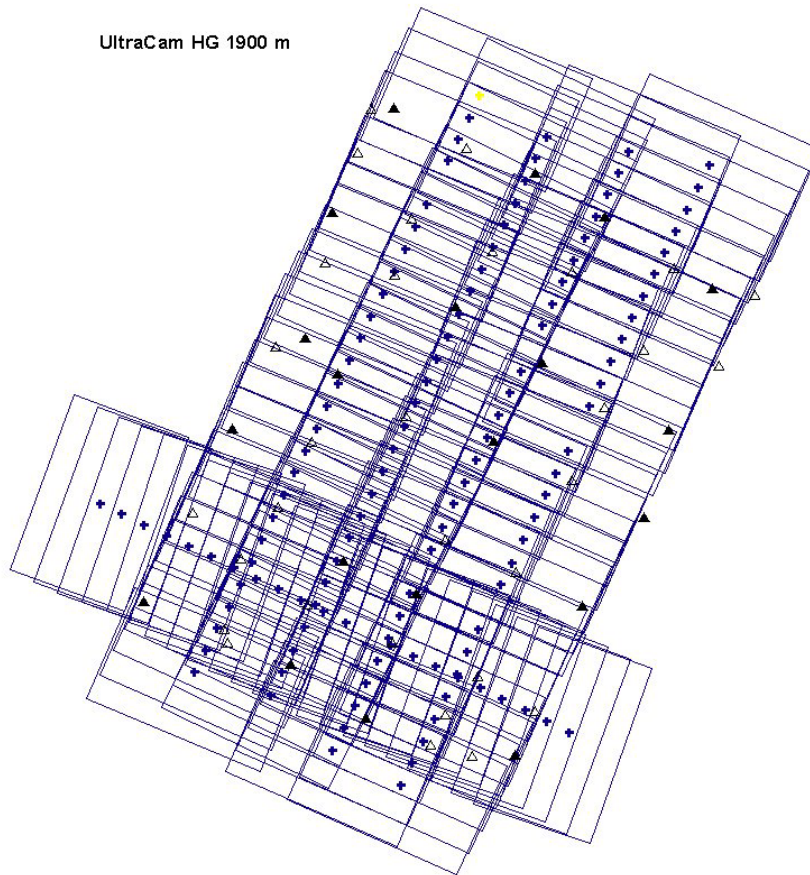
High (GSD 18cm, h=1800m)



UCD image block geometry

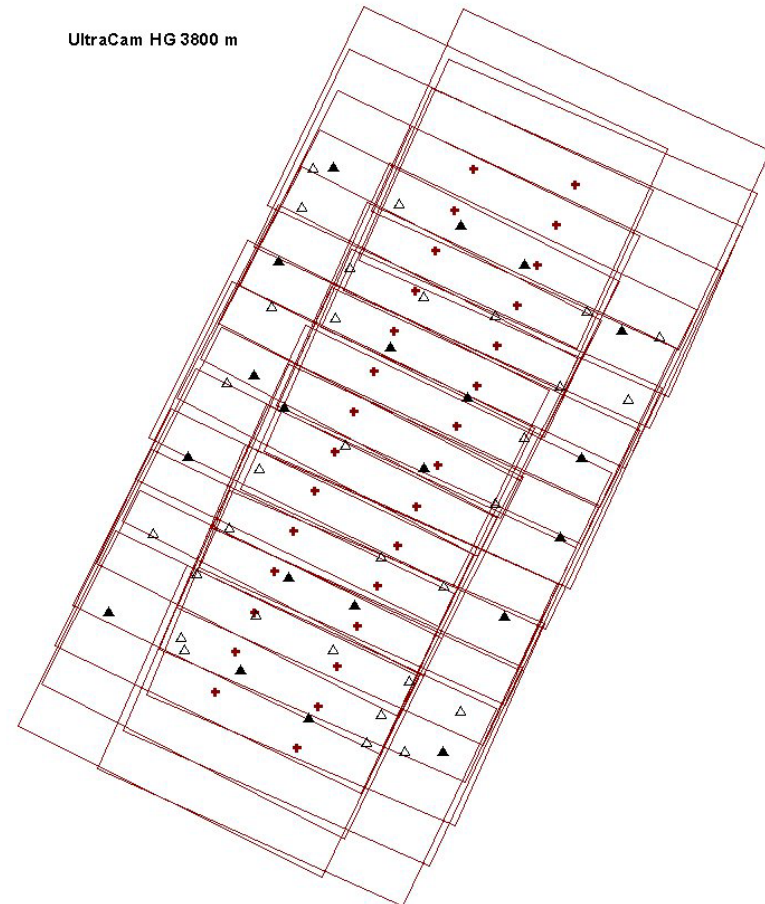


UltraCam HG 1900 m



Low (GSD 17cm, h=1900m)

UltraCam HG 3800 m



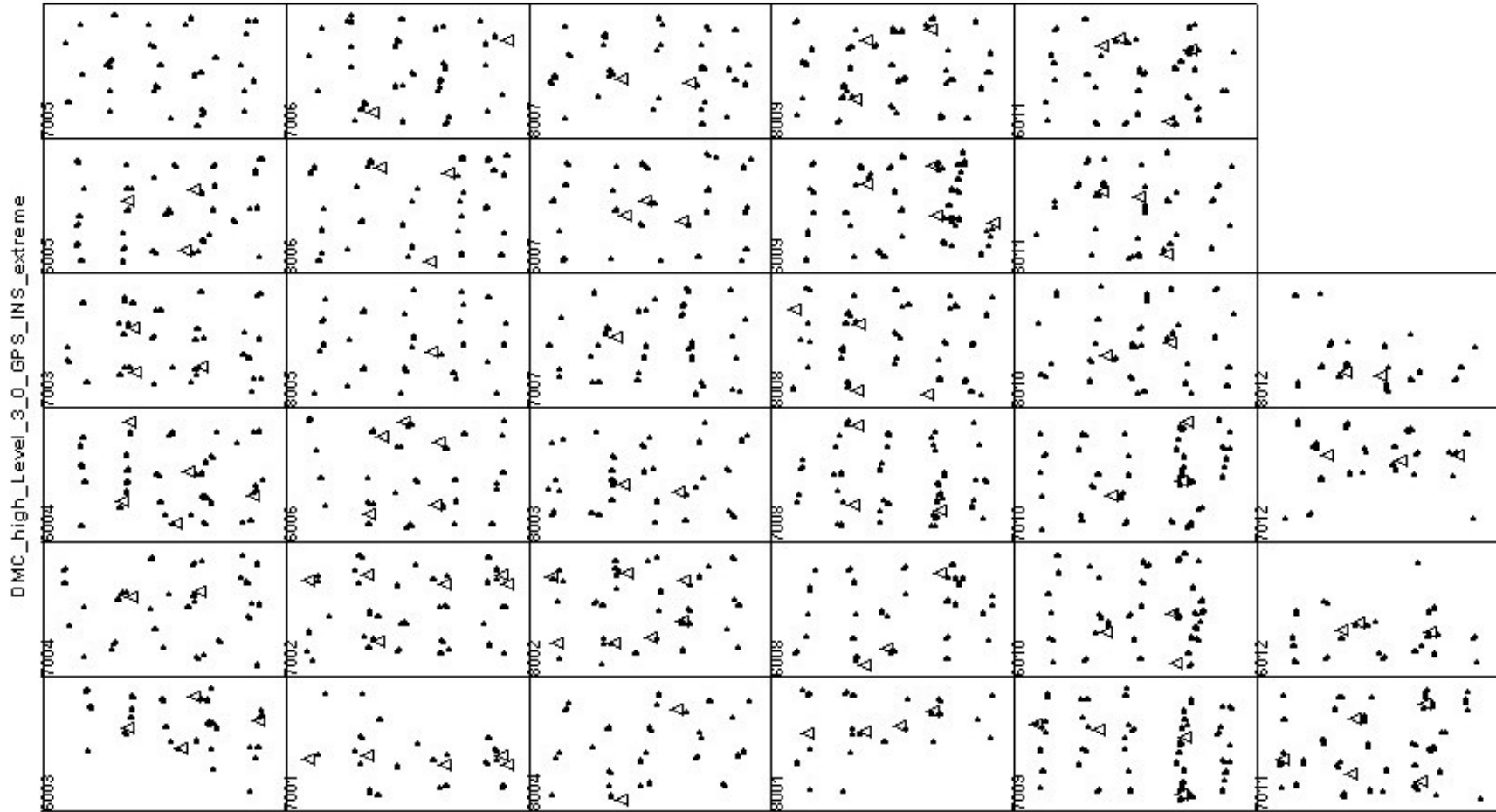
High (GSD 34cm, h=3800m)





Image coordinates by Pilot Centre

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Example DMC high measured points / image

Phase 2 / 2 b

Active Participants



#	Code	Institutions
1	ICC	Institute Cartographic Catalunya, Spain
2	LM	Lantmatäriet, Gävle, Sweden
3	itacyl	ITACYL, Valladolid, Spain
4	inpho	inpho, Stuttgart, Germany
5	CSIRO	CSIRO Information Sciences, Wembley, Australia
6	DLR-B	DLR, Berlin, Germany
7	HfT	University of Applied Science, Stuttgart, Germany
8	IPI	IPI, University of Hannover, Germany
9	ETH, <i>ETH</i>	ETH Zürich, Switzerland
10	UoP	University of Pavia, Italy

Phase 2 / 2 b

Active Participants



#	Code	Institutions
11	UoN	University of Nottingham, England
12	Ingr.ZI	Intergraph ZI, Aalen, Germany
13	<i>Vexcel</i>	<i>Vexcel, Graz, Austria</i>

Phase 2b results data

- **DMC** phase 2b processings

- **5 participants**
- 21 versions for high, 20 versions for low flight
- 5 versions for both flights

- **UCD** phase 2b processings

- **4 participants**
- 15 versions for low, 14 versions for high flight
- 5 versions for both flights

- overall **80 different variants** evaluated in phase 2b

normal

bold

italic

activities in phase 2

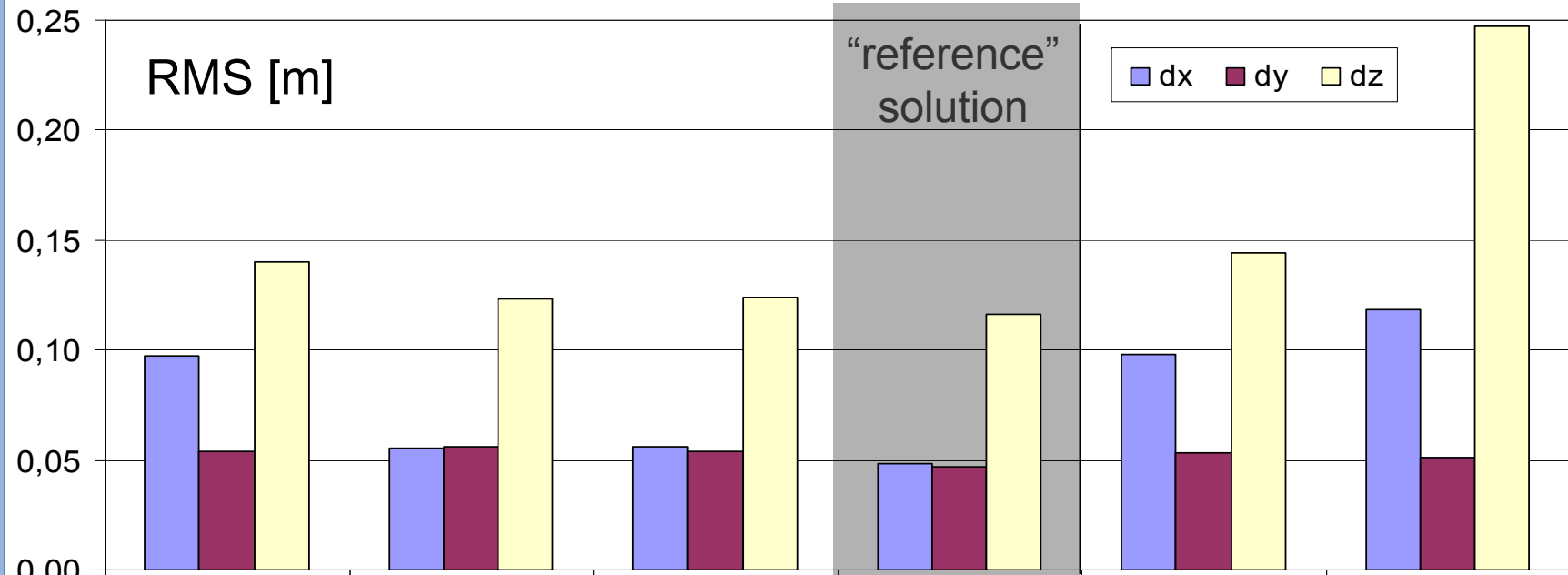
activities in phase 2 and 2b

activities in phase 2b



Phase 2b – DMC high, GSD 18cm

ifp solutions



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	ifp	ifp	ifp	ifp	ifp	ifp
	no	p44	p44 sign	p44 all cp	no	no
	dgap	dgap	dgap	dgap	patb	patb
STD [m]	0.02	0.02	0.02	0.02	0.02	0.01
GCPs.	0.02	0.02	0.02	0.02	0.02	0.01
STD [um]	3	3	3	3	3	3,6
Image pts.	3	3	3	3	3	1,2



Phase 2b

ifp "reference" solutions

Flight	H [m]	GSD [m]	RMS		
			X [m]	Y [m]	Z [m]
DMC	950	0.10	0.040	0.048	0.132
DMC	1800	0.18	0.048	0.047	0.116
UCD	1900	0.17	0.076	0.060	0.059
UCD	3800	0.34	0.048	0.068	0.103

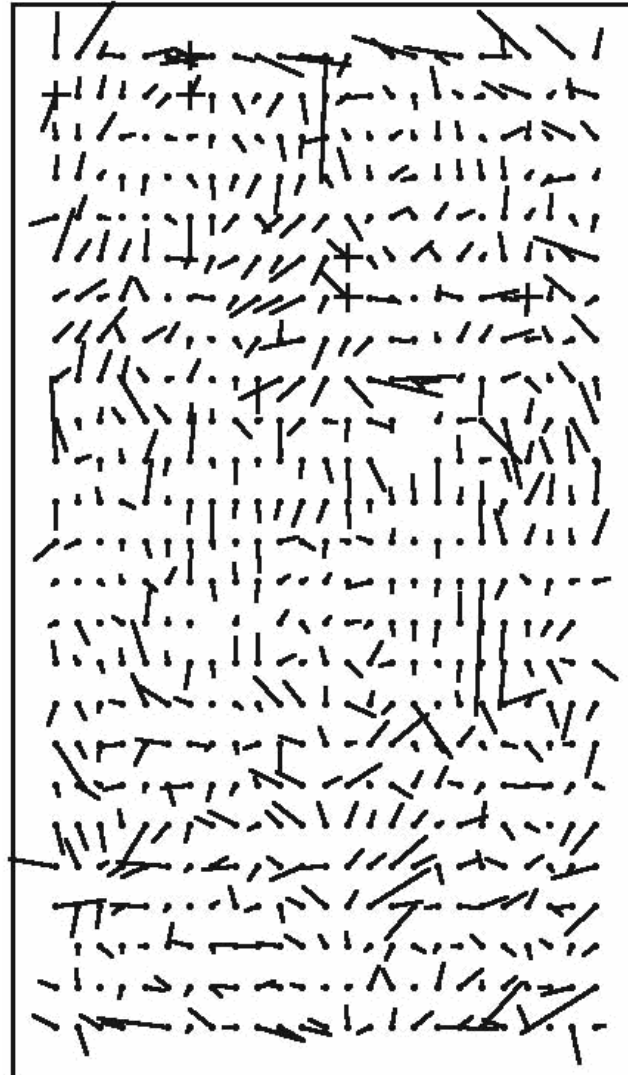
- RMS values from check point differences
- in all cases 44 significant Gruen parameters introduced, from all available ground points (GCPs and ChPs)
- Input std.dev. used for weighting:
 - image points 3um
 - GCPs 2cm



Image coordinate residuals AT without add. params

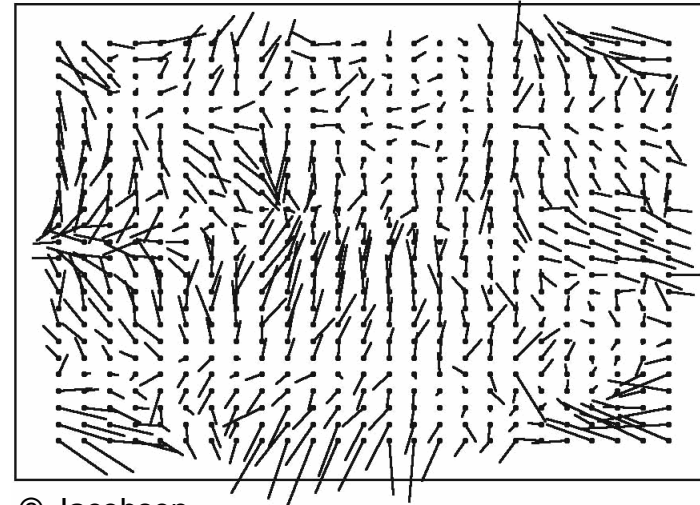


DMC



© Jacobsen

3.0



© Jacobsen

UCD 3.0

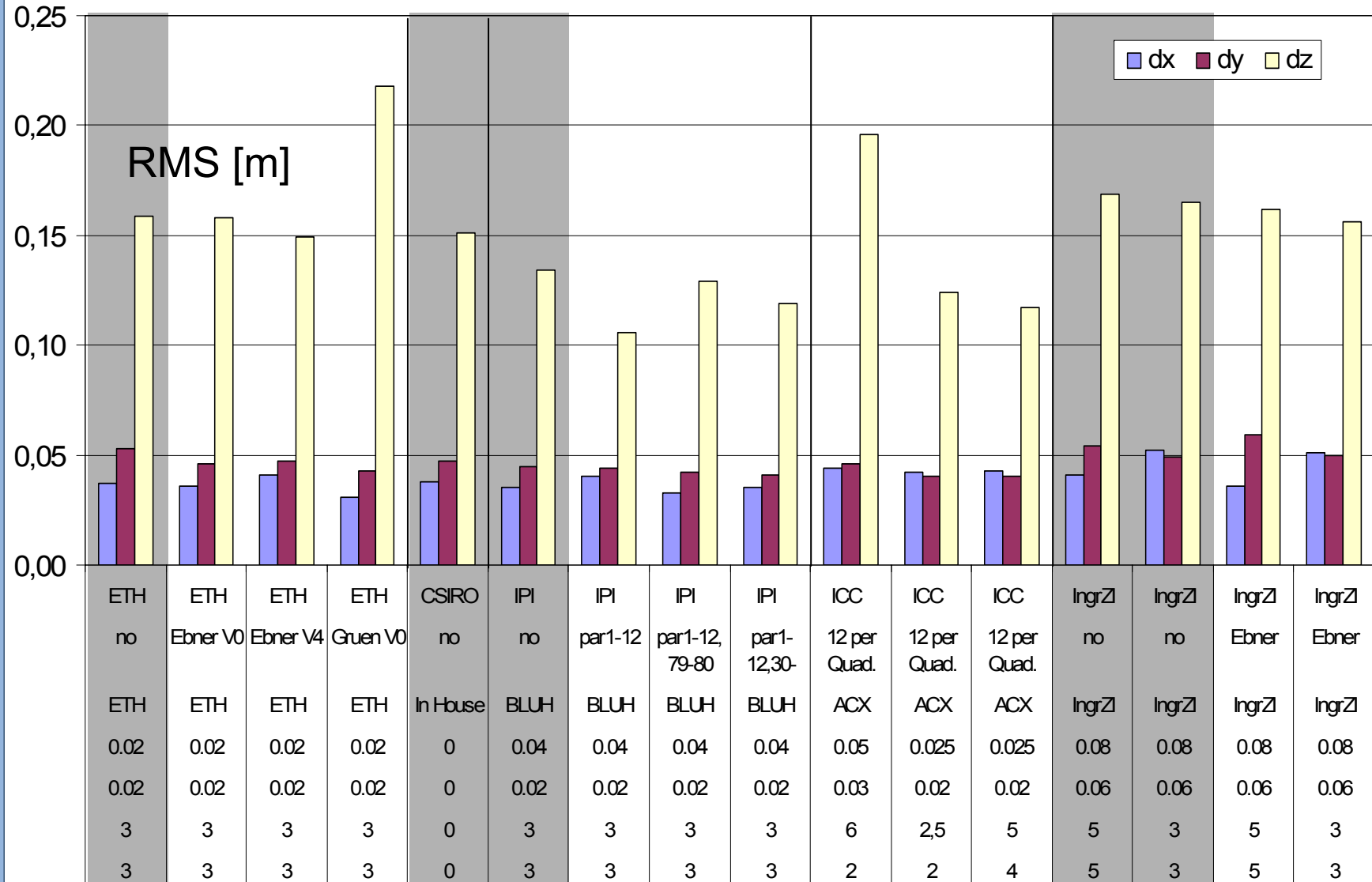
Overlay of residuals from both
flying heights (low & high)



Phase 2b – DMC low

GSD 10cm, hg 950m

No SC

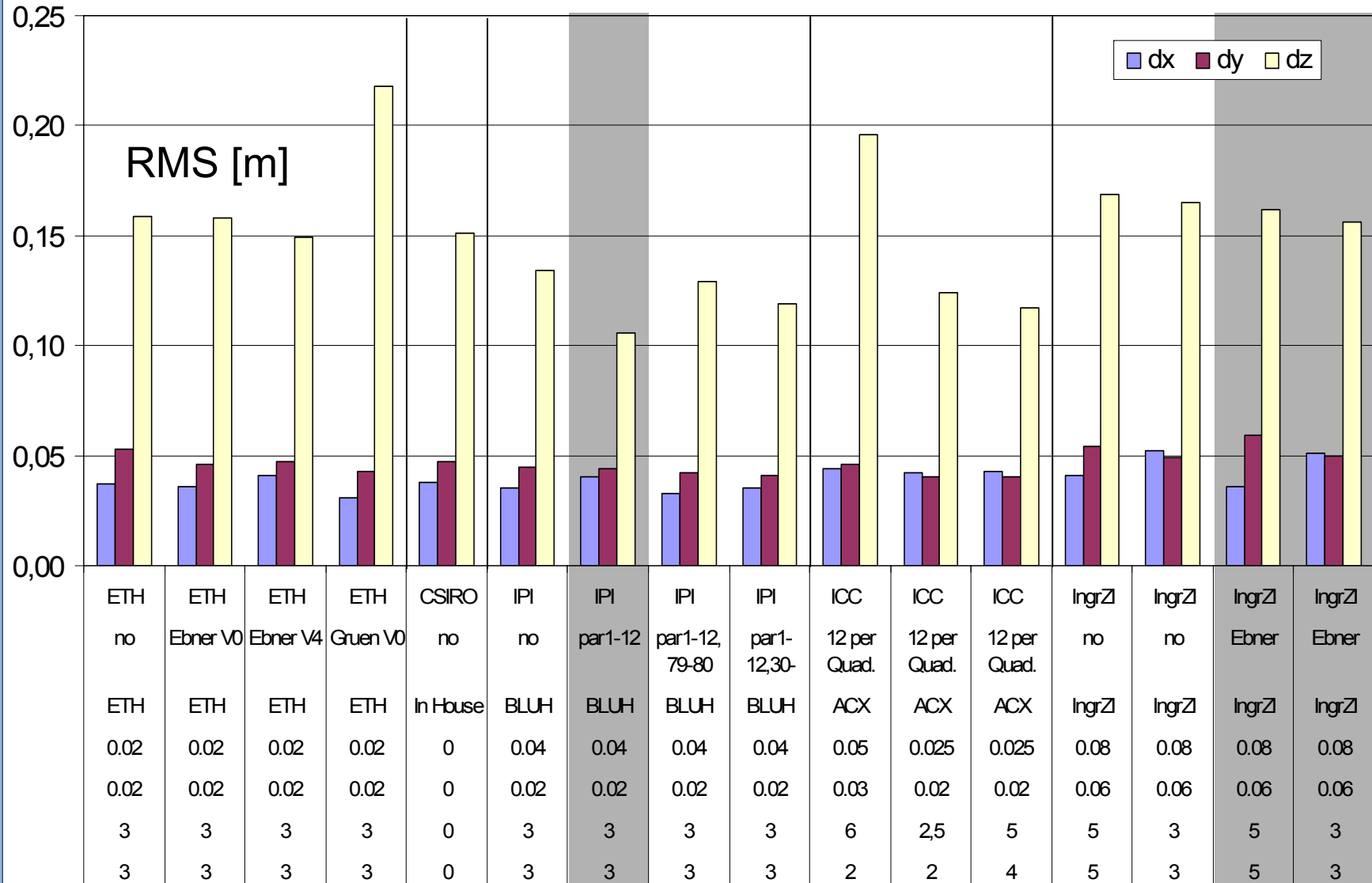




Phase 2b – DMC low

GSD 10cm, hg 950m

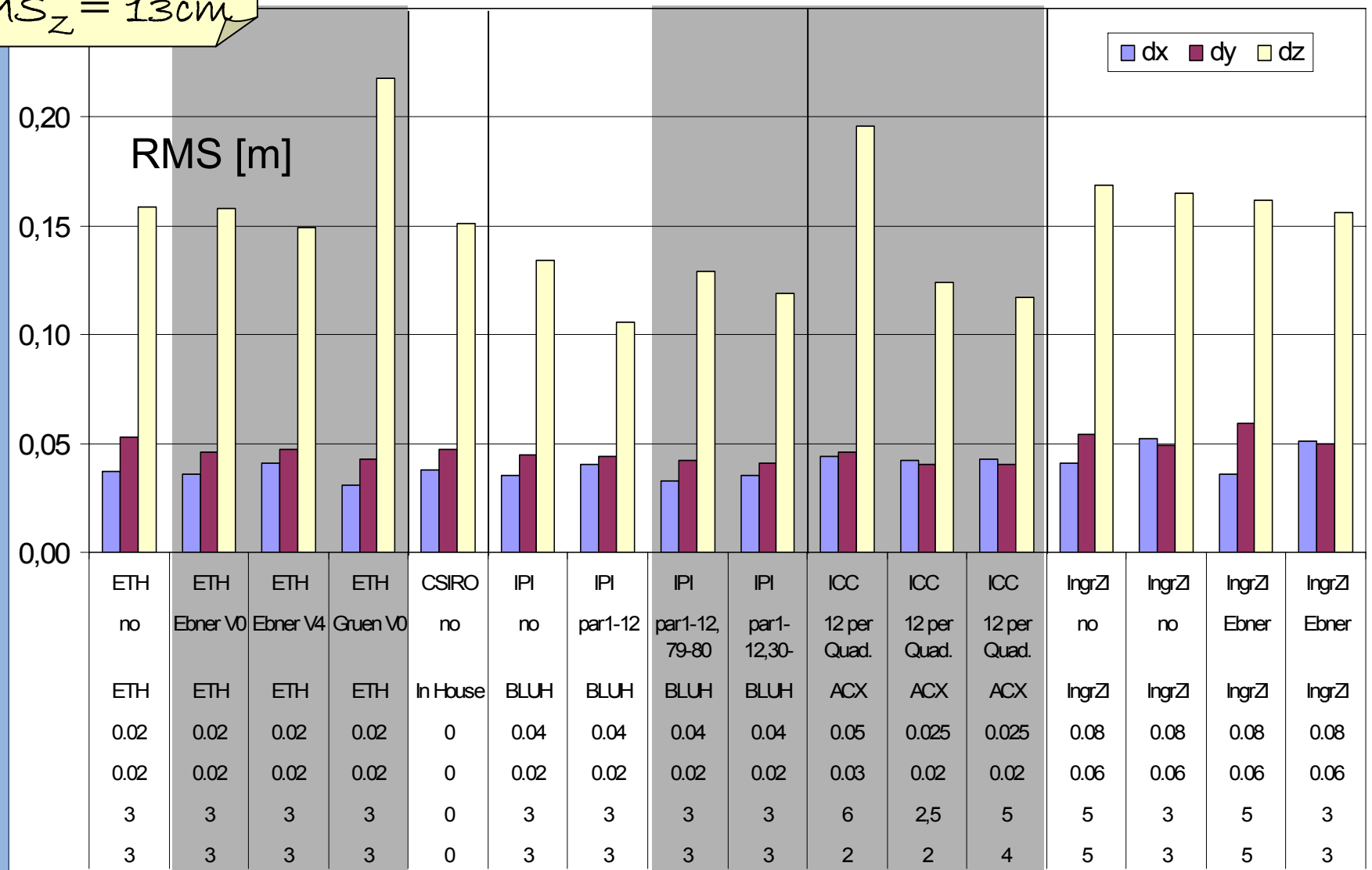
Standard params



ifp „reference“
 $RMS_x = 4cm$
 $RMS_y = 5cm$
 $RMS_z = 13cm$

Phase 2b – DMC low GSD 10cm, hg 950m

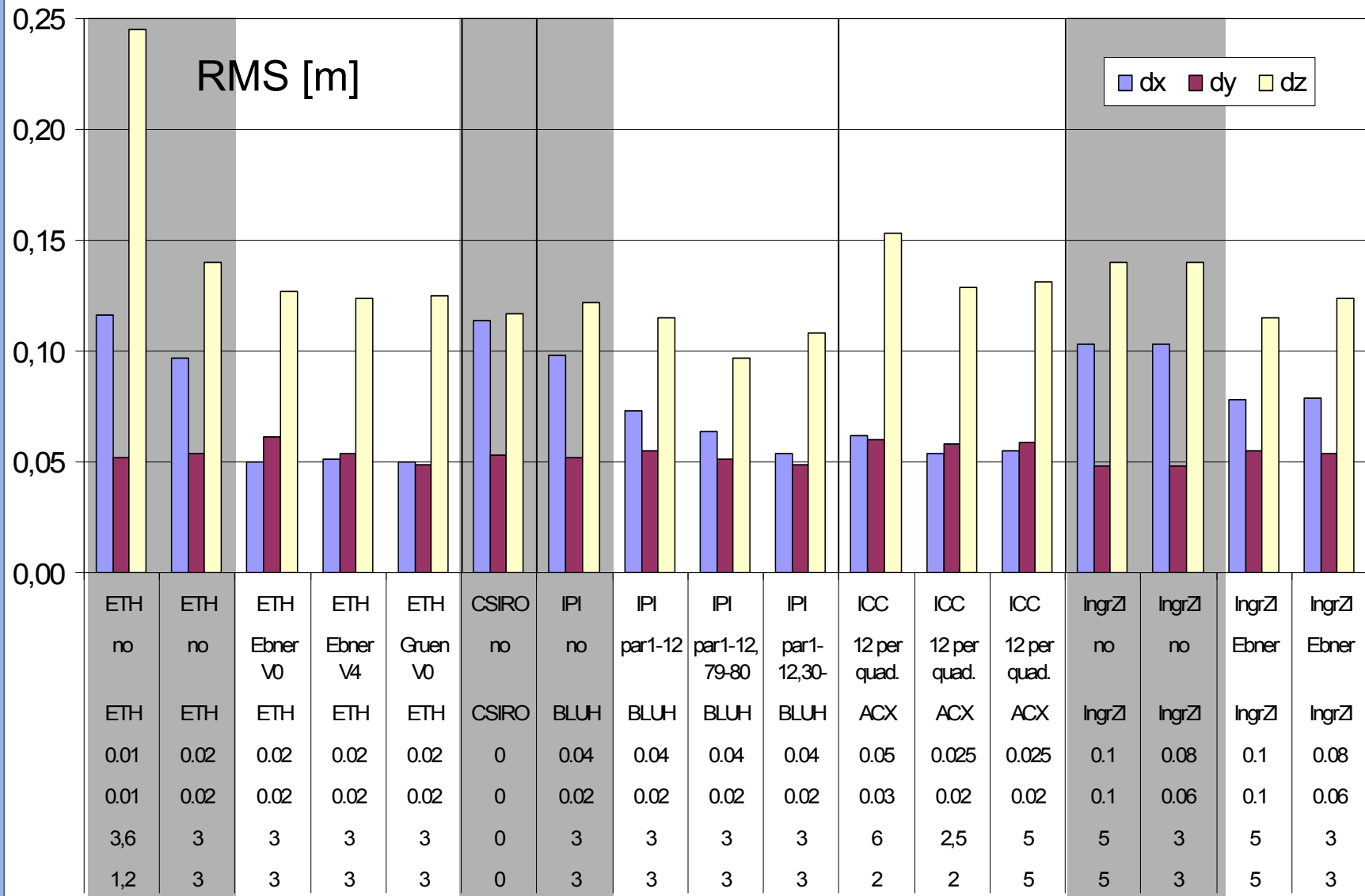
DMC specific



Phase 2b – DMC high

GSD 18cm, hg 1800m

No SC

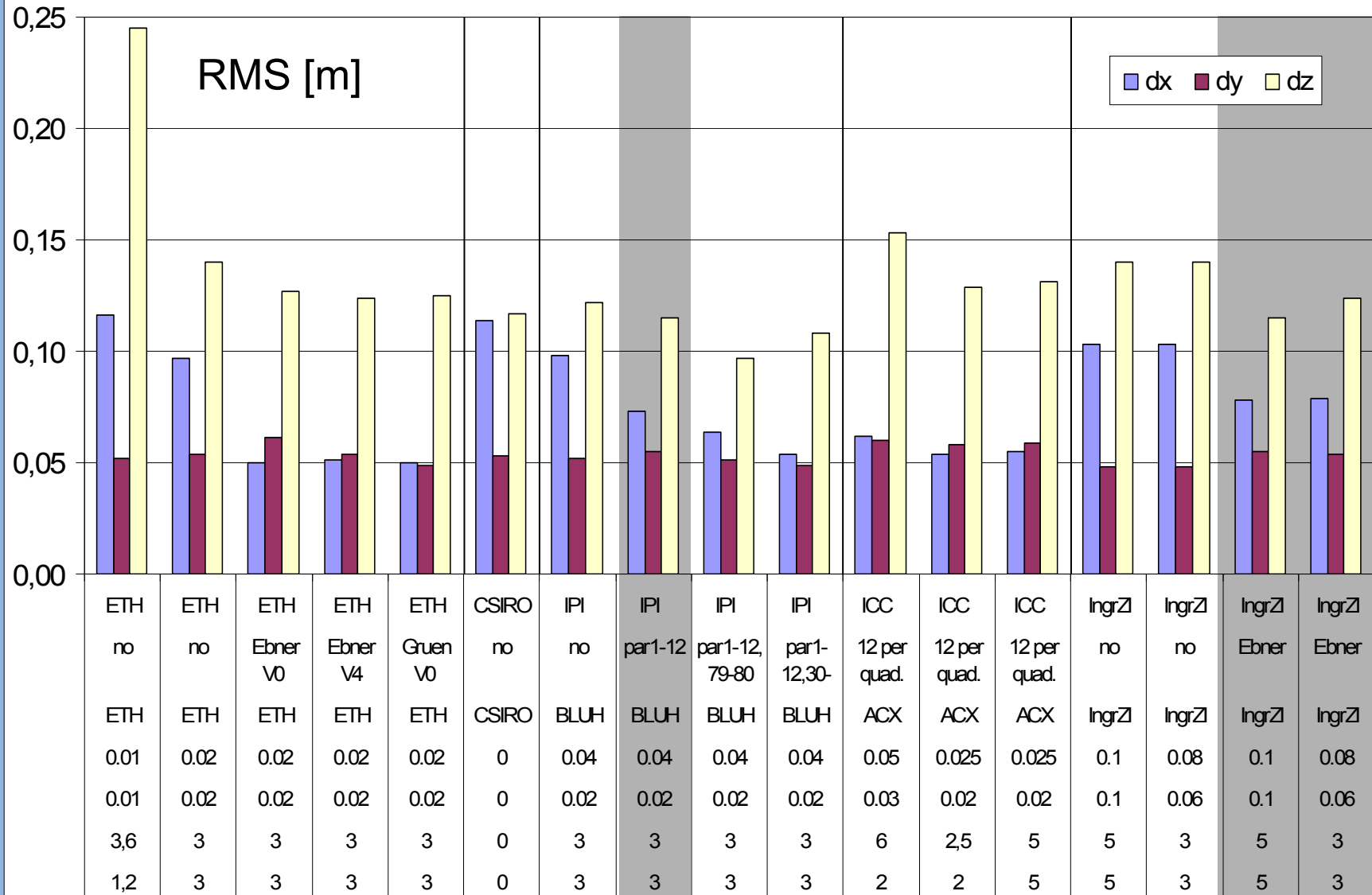




Phase 2b – DMC high

GSD 18cm, hg 1800m

Standard params



ifp „reference“

$$RMS_x = 5cm$$

$$RMS_y = 5cm$$

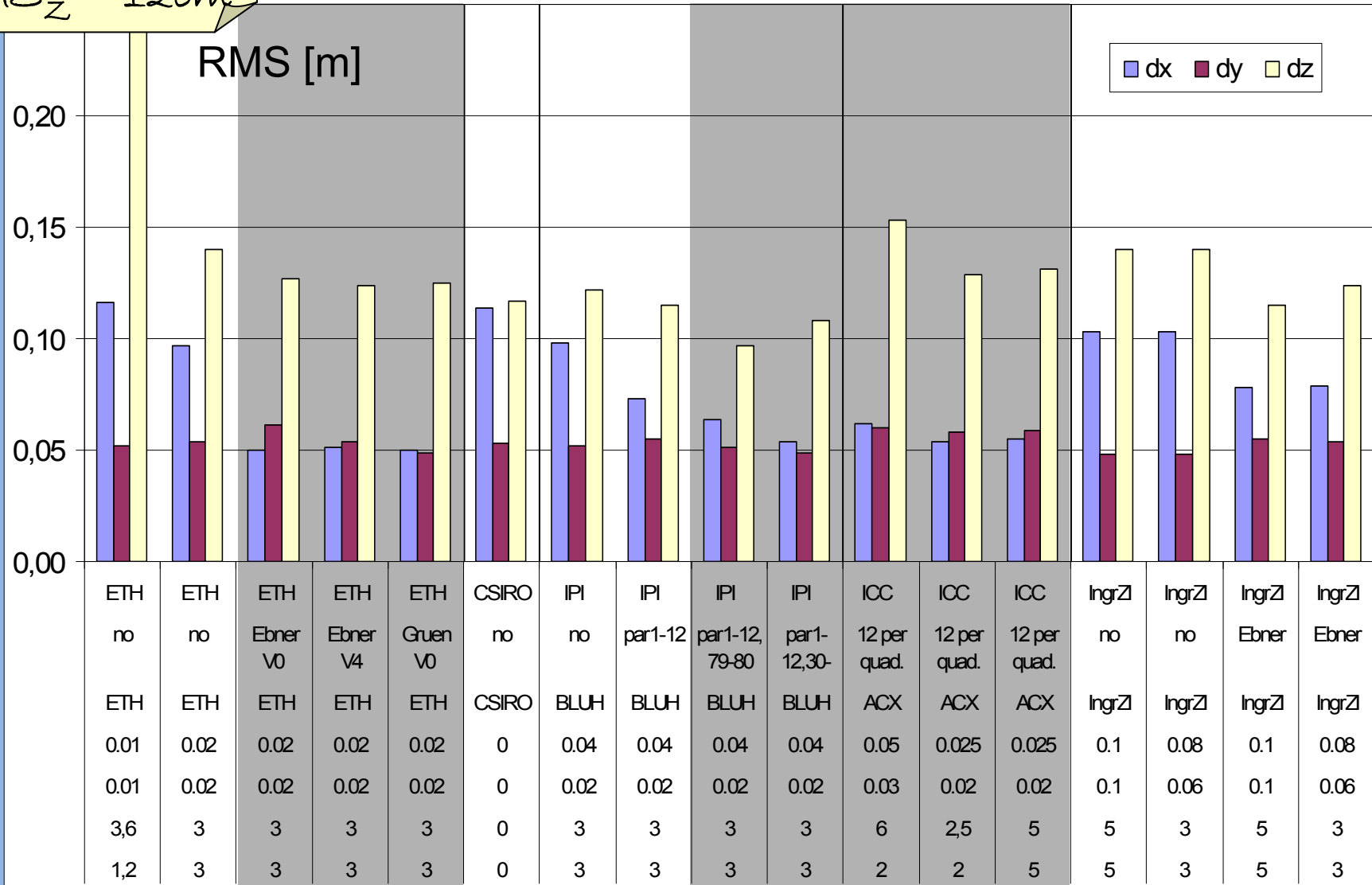
$$RMS_z = 12cm$$

Phase 2b – DMC high

GSD 18cm, hg 1800m

DMC params

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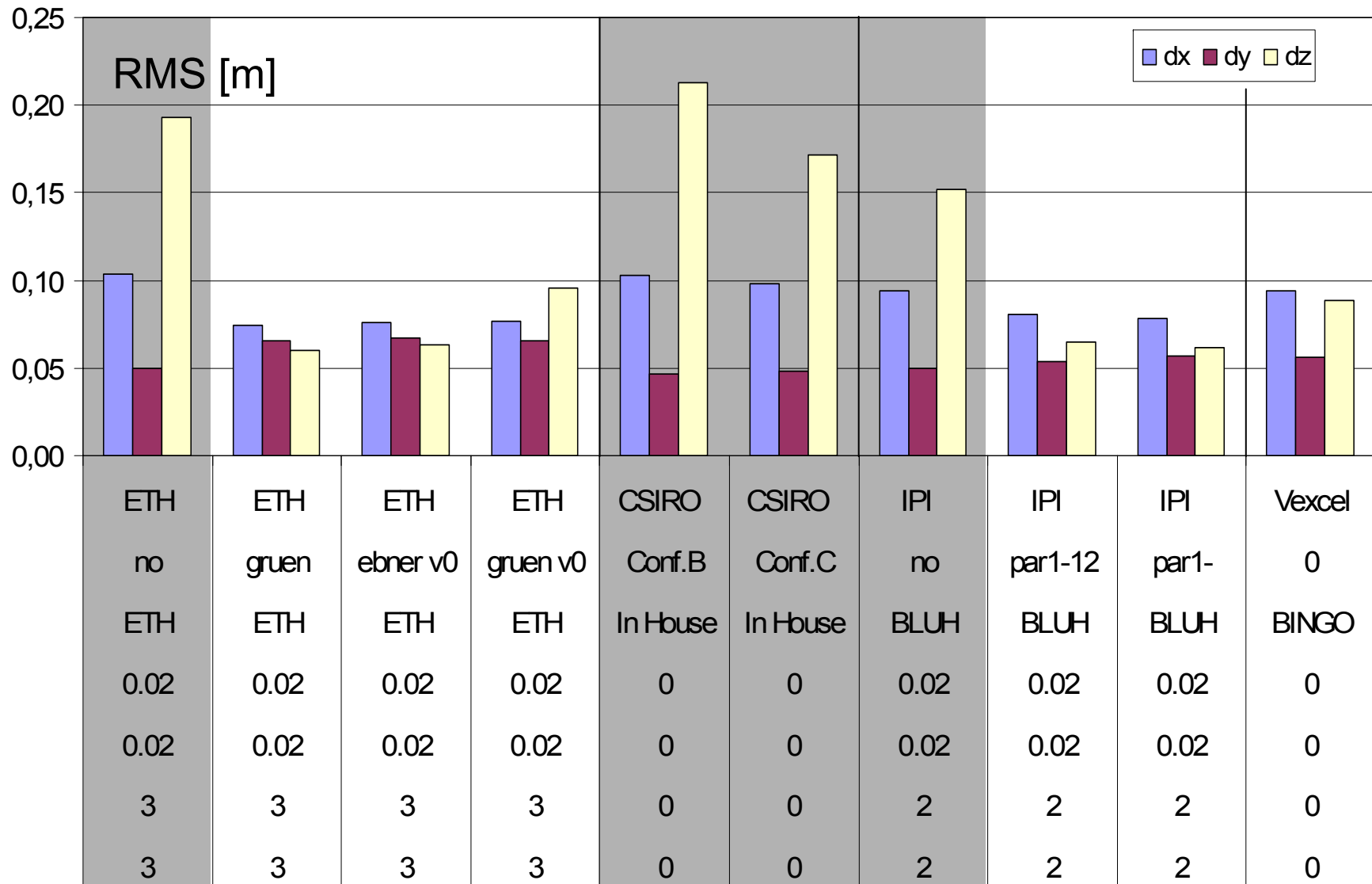




Phase 2b – UCD low

GSD 17cm, hg 1900m

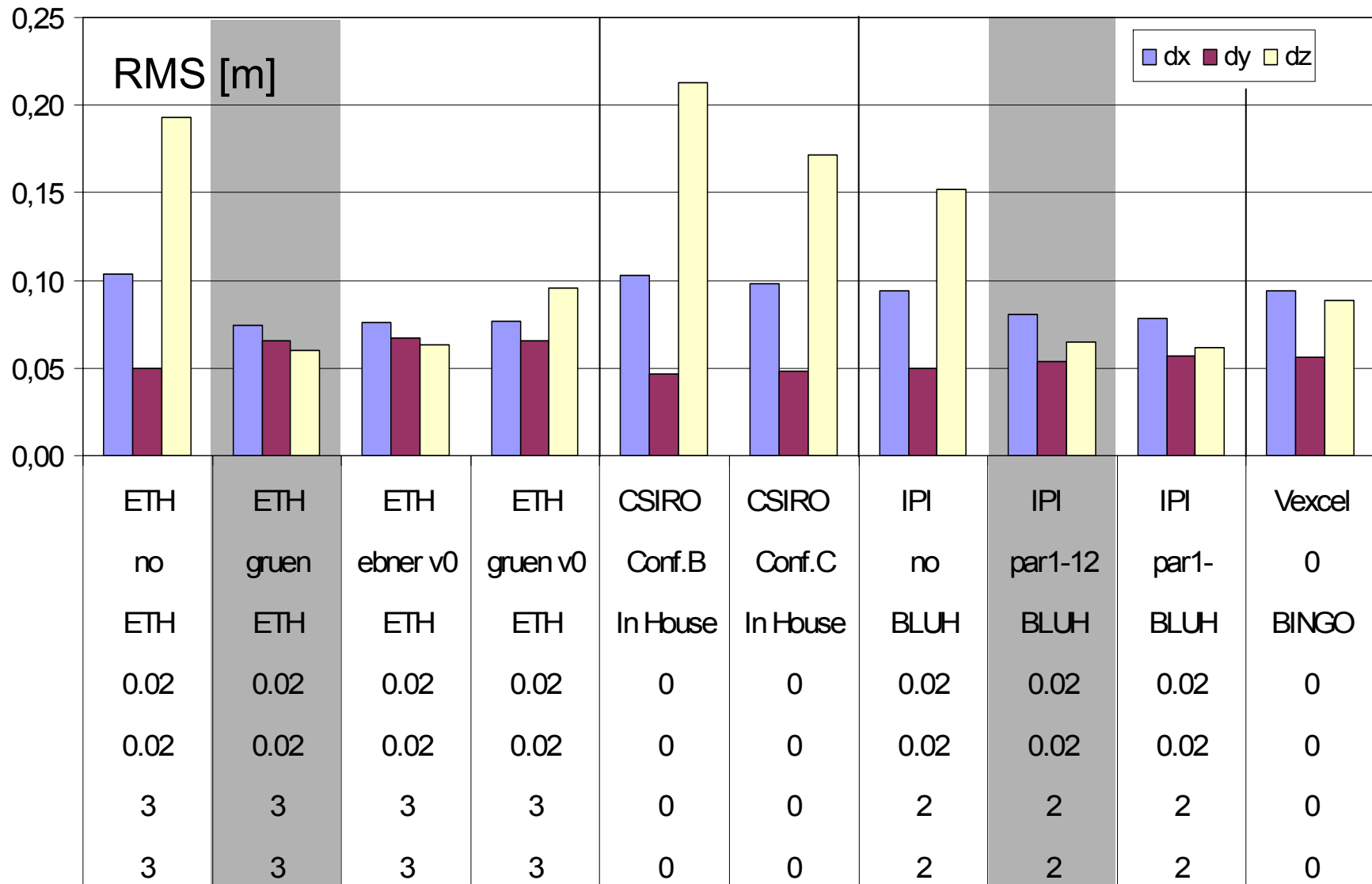
No SC



Phase 2b – UCD low

GSD 17cm, hg 1900m

Standard params

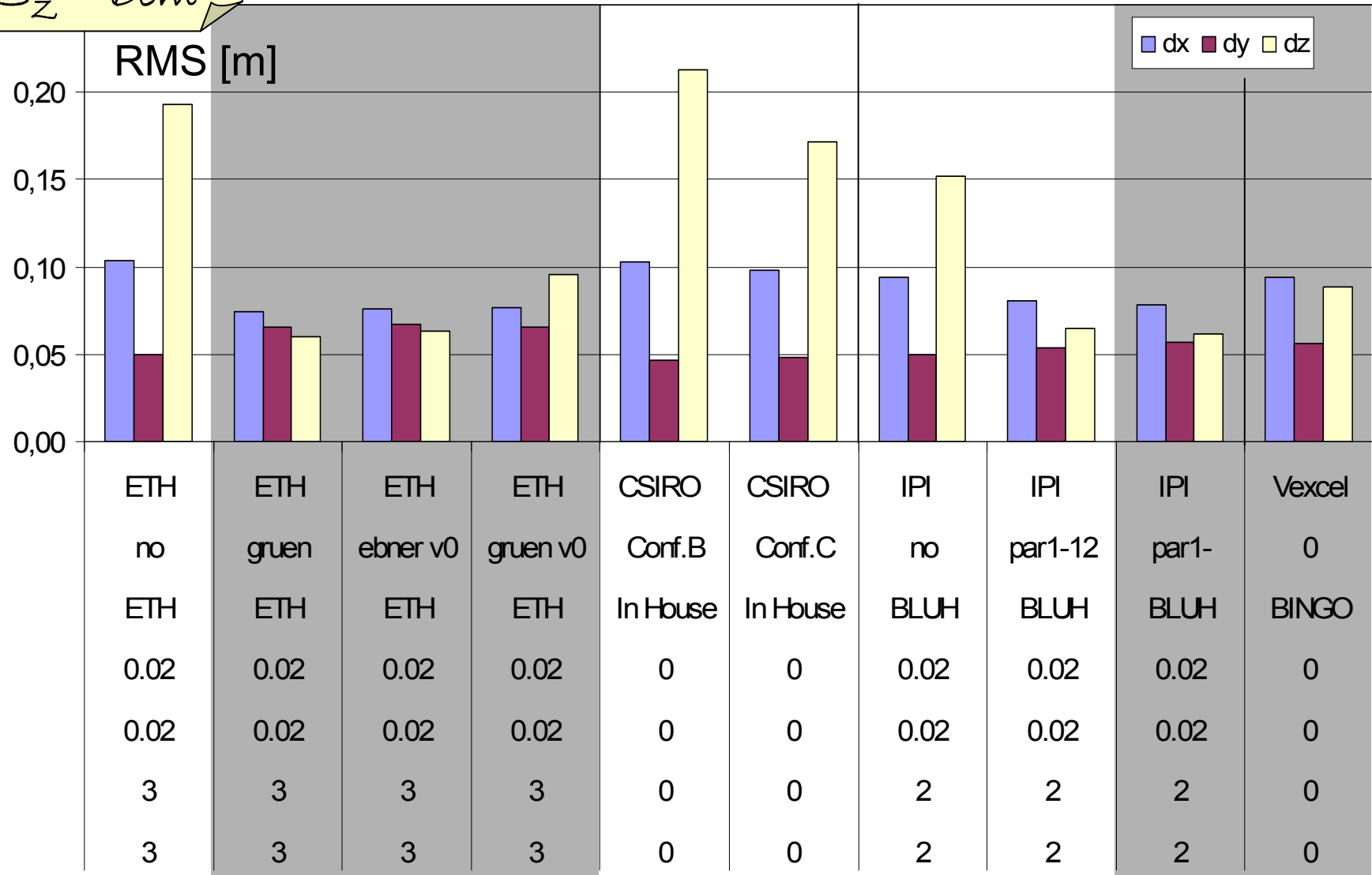


ifp „reference“
 $RMS_x = 8cm$
 $RMS_y = 6cm$
 $RMS_z = 6cm$

Phase 2b – UCD low

GSD 17cm, hg 1900m

UCD params

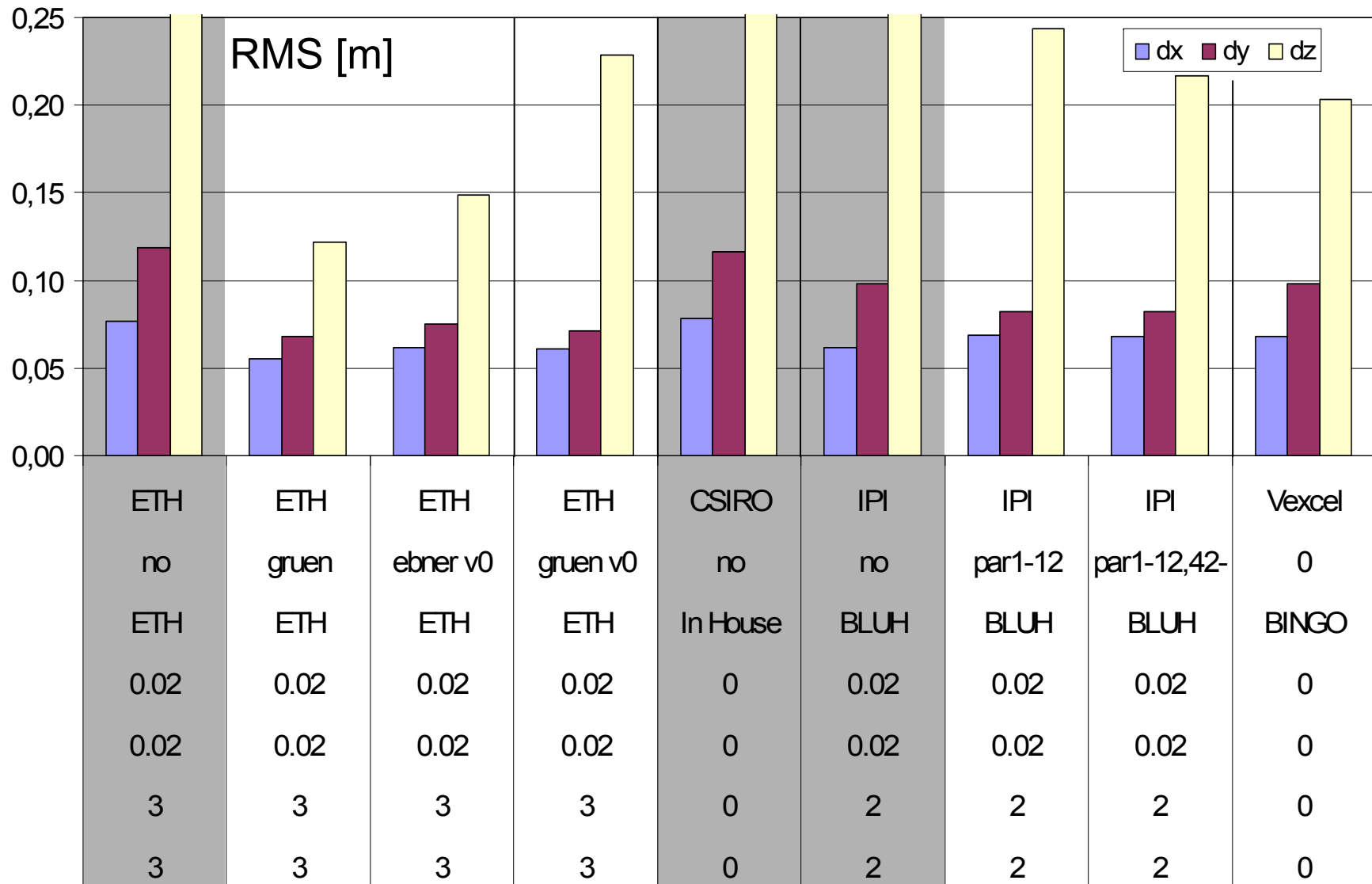




Phase 2b – UCD high

GSD 34cm, hg 3800m

No SC

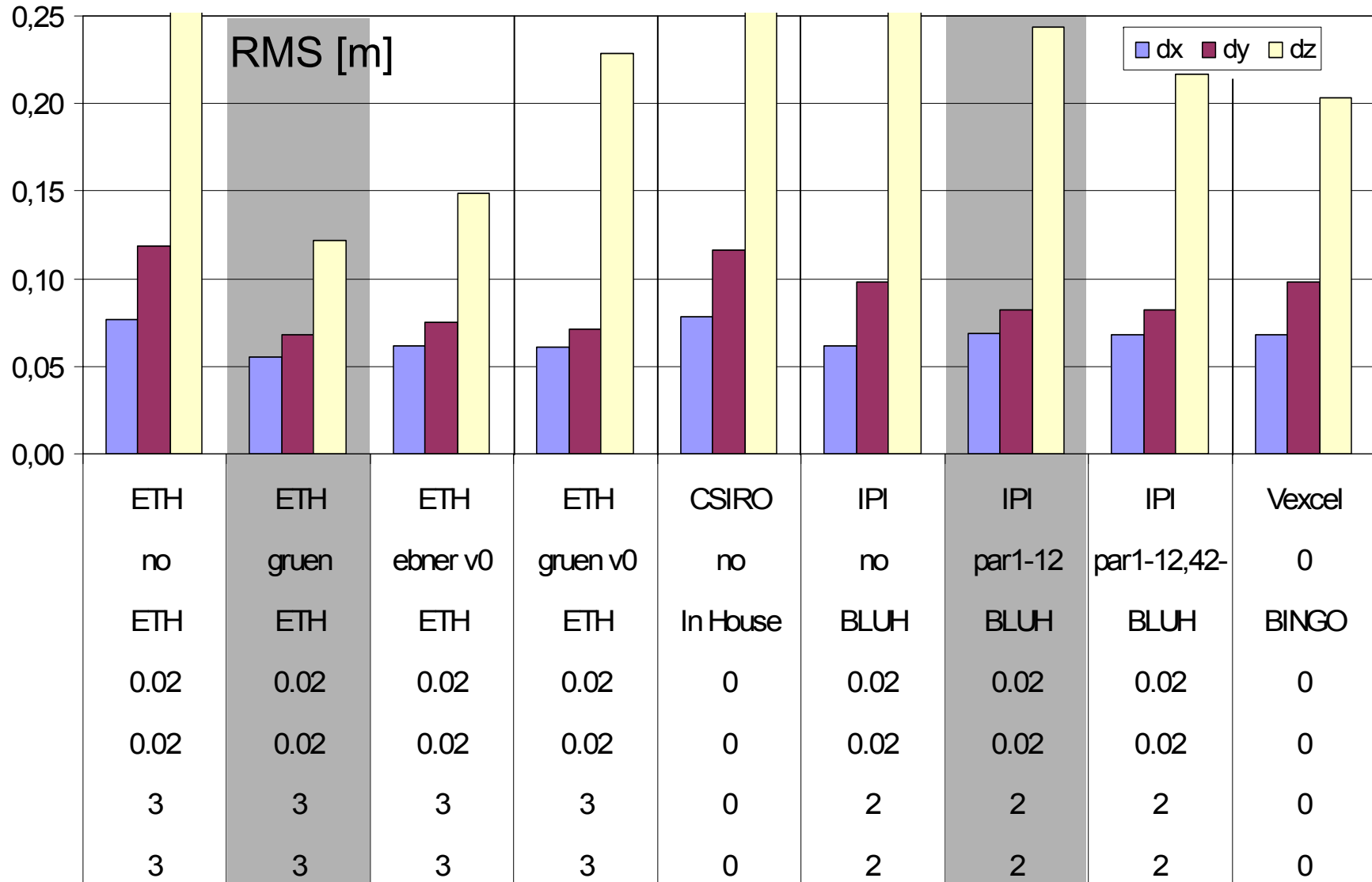




Phase 2b – UCD high

GSD 34cm, hg 3800m

Standard params

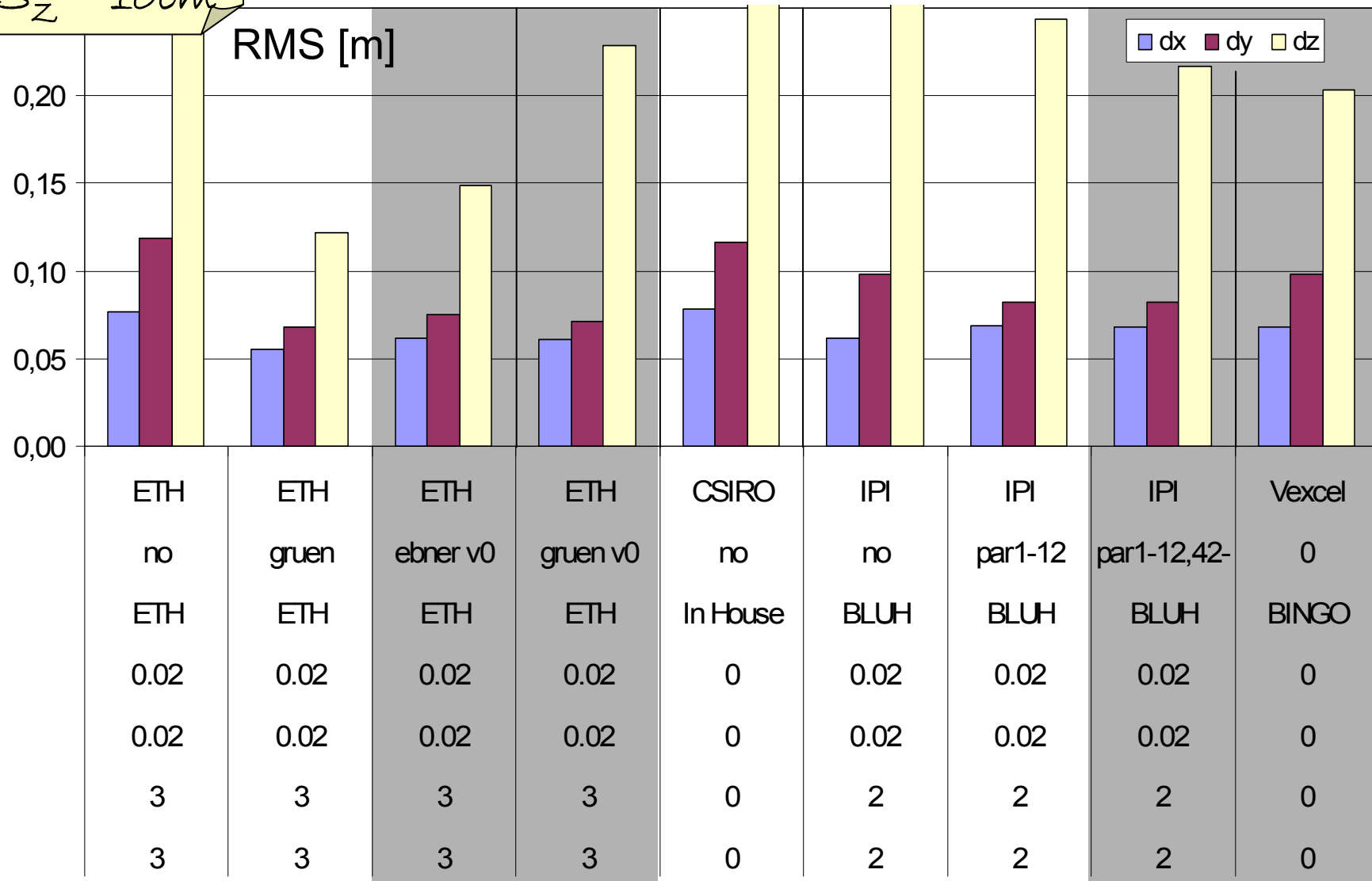


ifp „reference“
 $RMS_x = 5cm$
 $RMS_y = 7cm$
 $RMS_z = 10cm$

Phase 2b – UCD high

GSD 34cm, hg 3800m

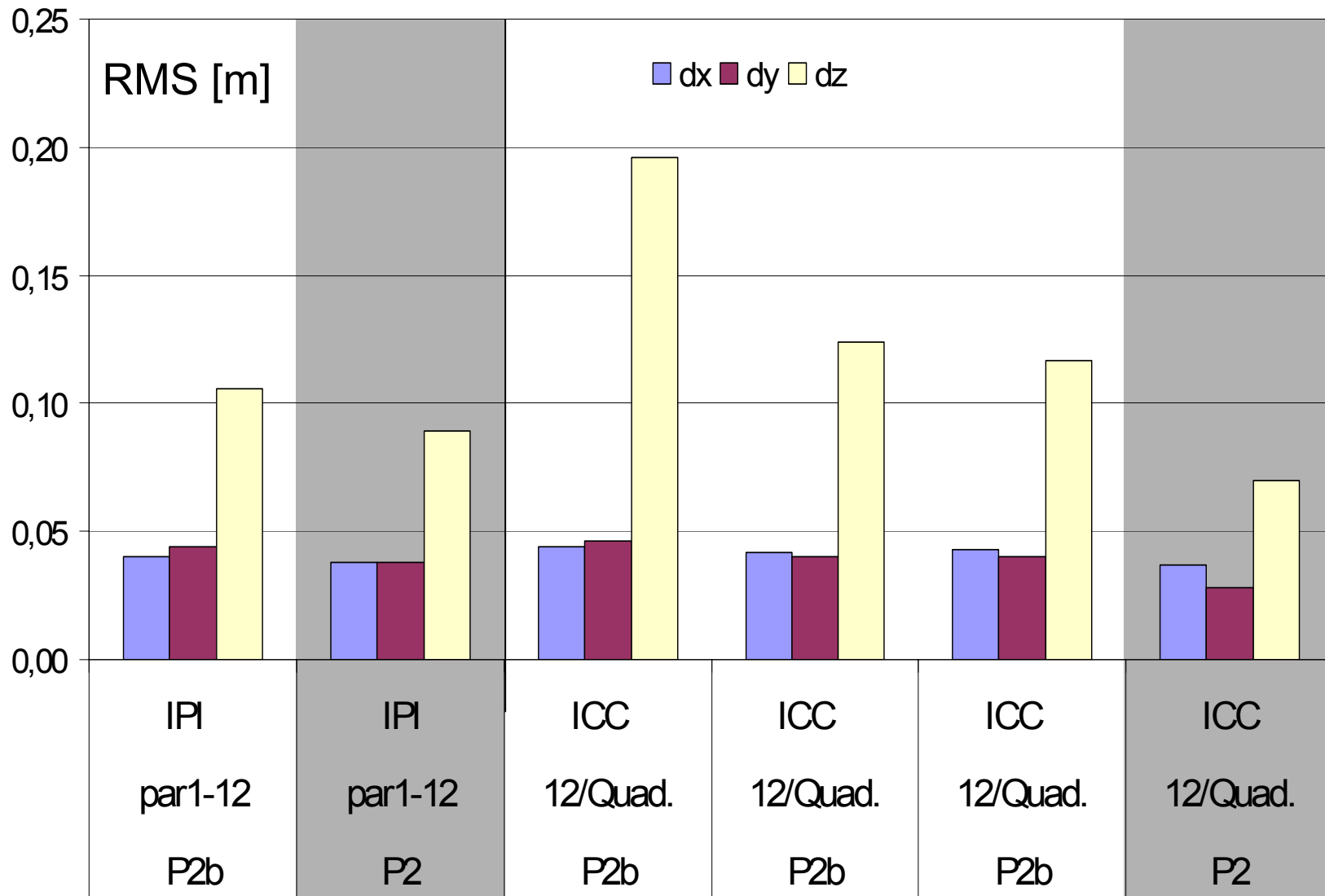
UCD params





Phase 2b vs. Phase 2

DMC low block



Summary

Results from Phase 2b



- **self-calibration is necessary in all cases to achieve optimal result**
- a priori weightings are also of influence, in some cases choice of weighting factors exceeds effect of additional parameter set
- in some cases special parameter sets adopted to sensor geometry seem to be necessary, although standard sets like Ebner or Gruen already compensate large portion of systematic error budget, i.e.
 - for UCD flights Gruen 44 params perform very well, same accuracy or even better than UC specific correction terms
 - for DMC low flight 12 standard BLUH params are mostly sufficient, amended by two additional DMC params for high flight
- a priori **recommendation of optimal additional parameter set is difficult** or even not possible





Summary

Project Camera Calibration

- **Phase 2b analyses now finalize project activities!**
- Final report to be compiled in fall 2007 (should be part of EuroSDR publication #53).
- Presentation / publication of project results
 - European DMC user meeting Gävle, Sweden (Jan 2007)
 - ISPRS workshop Hannover, Germany (May 2007)
 - Photogrammetric Week, Stuttgart, Germany (September 2007)
 - RSPoc annual meeting, Newcastle, UK (September 2007)
 - Journal publication
- Compilation of EduServ 2008 module, which is mostly based on project data, experiences and results

